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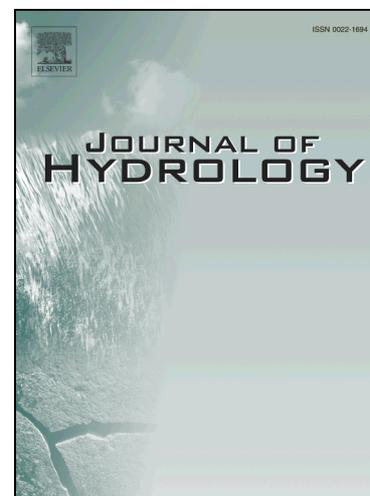
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1 **Impact of model structure and parameterization on Penman-Monteith type**
2 **evaporation models**

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15 **Abstract**

16 The impact of model structure and parameterization on the estimation of evaporation is
17 investigated across a range of Penman-Monteith type models. To examine the role of model
18 structure on flux retrievals, three different retrieval schemes are compared. The schemes include a
19 traditional single-source Penman-Monteith model (Monteith, 1965), a two-layer model based on
20 Shuttleworth and Wallace (1985) and a three-source model based on Mu et al. (2011). To assess the
21 impact of parameterization choice on model performance, a number of commonly used
22 formulations for aerodynamic and surface resistances were substituted into the different

23 formulations. Model response to these changes was evaluated against data from twenty globally
24 distributed FLUXNET towers, representing a cross-section of biomes that include grassland, cropland,
25 shrubland, evergreen needleleaf forest and deciduous broadleaf forest.

26 Scenarios based on 14 different combinations of model structure and parameterization were ranked
27 based on their mean value of Nash-Sutcliffe Efficiency. Results illustrated considerable variability in
28 model performance both within and between biome types. Indeed, no single model consistently
29 outperformed any other when considered across all biomes. For instance, in grassland and
30 shrubland sites, the single-source Penman-Monteith model performed the best. In croplands it was
31 the three-source Mu model, while for evergreen needleleaf and deciduous broadleaf forests, the
32 Shuttleworth-Wallace model rated highest. Interestingly, these top ranked scenarios all shared the
33 simple lookup-table based surface resistance parameterization of Mu et al. (2011), while a more
34 complex Jarvis multiplicative method for surface resistance produced lower ranked simulations. The
35 highly ranked scenarios mostly employed a version of the Thom (1975) formulation for aerodynamic
36 resistance that incorporated dynamic values of roughness parameters. This was true for all cases
37 except over deciduous broadleaf sites, where the simpler aerodynamic resistance approach of Mu et
38 al. (2011) showed improved performance.

39 Overall, the results illustrate the sensitivity of Penman-Monteith type models to model structure,
40 parameterization choice and biome type. A particular challenge in flux estimation relates to
41 developing robust and broadly applicable model formulations. With many choices available for use,
42 providing guidance on the most appropriate scheme to employ is required to advance approaches
43 for routine global scale flux estimates, undertake hydrometeorological assessments or develop
44 hydrological forecasting tools, amongst many other applications. In such cases, a multi-model
45 ensemble or biome-specific tiled evaporation product may be an appropriate solution, given the
46 inherent variability in model and parameterization choice that is observed within single product
47 estimates.

48 **Keywords:** latent heat flux; evaporation; evapotranspiration; Penman-Monteith; surface resistance;
49 aerodynamic resistance

50 **1 Introduction**

51 Accurate estimates of evaporation are required in water resources management, irrigation
52 management and hydrologic studies. For this reason, a range of models have been developed to
53 provide evaporation products across different spatial and temporal scales (Kalma et al., 2008; Wang
54 and Dickinson, 2012). The Penman-Monteith (PM) model (Monteith, 1965) is one of the most widely
55 employed approaches for the estimation of evaporation, as it has a process-based formulation that
56 utilises commonly available meteorological variables, including air temperature, wind speed,
57 humidity and radiation. The PM model forms the theoretical basis of a number of continental and
58 global scale evaporation models (Ferguson et al., 2010; Mu et al., 2011) and land surface schemes
59 (Chen and Dudhia, 2001), albeit with some variations in formulation and parameterization.

60 Underlying the performance of this common approach are important issues of model structure and
61 parameterization that influence the utility of the technique for general application. In its simplest
62 form, the Penman-Monteith model is a single-source “big-leaf” model that lumps the heterogeneity
63 of the land surface into a single evaporative element. In this configuration, no distinction is made
64 between evaporation from bare soil, evaporation from canopy intercepted water or transpiration via
65 the canopy (processes encompassed herein via the term evaporation, following the definition in
66 Kalma et al., 2008). However, other versions of the PM model have been developed that consider
67 the land surface as a layered system (e.g. Shuttleworth and Wallace, 1985) or discriminate
68 components of the land surface into different evaporative sources (e.g. soil and canopy), with a PM
69 model formulated in each layer or component (e.g. Mu et al., 2011).

70 Inherent in the choice of model structure is the development and selection of appropriate
71 parameterizations to describe the physical processes occurring within the system. In PM type

72 models, the aerodynamic (r_a) and surface resistance (r_s) schemes represent critical controls on heat
73 and vapor flux transfer through the soil, plant and atmospheric continuum. Given the importance of
74 the resistance parameterization in flux estimation (McCabe et al., 2005), a number of studies have
75 examined various resistance parameterization techniques in PM type models. The underlying
76 assumption in many of these studies has been that if the resistance parameters are estimated
77 accurately, then the (single-source) PM type model should be able to provide an accurate estimate
78 of evaporation (Raupach and Finnigan, 1988). Of course, the challenge is that direct independent
79 measurement of resistances is difficult, so discriminating good parameterizations from bad is not
80 trivial.

81 In addition to uncertainties that originate from inadequate surface resistance and aerodynamic
82 resistance formulations, the single-source structure of the PM model can also cause errors in
83 estimating evaporation. In terms of model structure, the single-source PM model was originally
84 developed for the special case of a dense, well-watered canopy that absorbs most of the available
85 energy. However, in sparse canopies, evaporation from the soil can be as important as the canopy
86 transpiration (Shuttleworth and Wallace, 1985). In these scenarios, the partitioning of total
87 evaporation to different sources or layers is important (Allen et al., 2011). Furthermore, the “big-
88 leaf” assumption requires that the sources of heat and water vapour occur at the same level within
89 the canopy (Finnigan et al., 2003; Foken et al., 2012). This requirement might be met in a short and
90 dense canopy or a bare soil surface, but is unlikely to be true for a tall or sparse canopy (Wallace,
91 1995).

92 As a consequence of these limitations and a desire to develop approaches with more general or
93 universal application, a number of efforts have been directed towards improving the structure of the
94 single source PM model to multi-layer or multi-source schemes. In a multi-layer scheme, the
95 representation of the soil-canopy-atmosphere system is improved by vertically dividing the canopy
96 structure into separate layers, with each utilizing the PM model, but linked via a network of

97 resistances. Such a multi-layer configuration means that the resistances are coupled in series and
98 have interactions (Shuttleworth and Wallace, 1985; Choudhury and Monteith, 1988). In multi-source
99 schemes, the total evaporation from the land surface is generally partitioned into evaporation from
100 the soil, transpiration from the canopy and evaporation from the intercepted water in the canopy
101 (with the latter absent in two-layer schemes). In contrast to multi-layer schemes, multi-source
102 schemes have resistances that are often in parallel and hence have no interaction.

103 Relatively few studies have focused on an intercomparison of PM based models to evaluate the
104 significance and effectiveness of both the model structure and the choice of parameterization
105 (Stannard, 1993; Huntingford et al., 1995; Fisher et al., 2005). In reviewing the literature it is readily
106 apparent that there are few definitive outcomes with which to guide the selection of the most
107 appropriate model configuration for a particular land surface. A missing element of many previous
108 efforts was a comprehensive examination of model and data characteristics, such as the role of
109 model structure (e.g. single-source, multi-layer, multi-source), impact of model parameterizations
110 (e.g. resistances and roughness) and variability in climate zone and biome type (e.g. grassland,
111 cropland, forest). Furthermore, most studies were performed over relatively short periods of weeks
112 to months (e.g. Stannard, 1993; Huntingford et al., 1995) as a consequence of data limitations, with
113 few cases extending into yearly time periods (e.g. Fisher et al., 2005; Ortega-Farias et al., 2010).
114 Clearly, multi-year datasets are better able to represent the dynamics in the bio-physiological and
115 hydro-meteorological variability of the land surface: issues that are central in evaporation estimation
116 and comprehensive model evaluation.

117 These issues provide the motivation to evaluate the role of model structure and parameterization
118 across a range of PM type models. For this purpose, we selected three model structures: the original
119 single-source Penman-Monteith model (Monteith, 1965), a modified two-layer model (Shuttleworth
120 and Wallace, 1985) and a three-source model (Mu et al., 2011). Each scheme was then adjusted to
121 incorporate a variety of aerodynamic and surface resistance parameterizations. To maintain a

122 realistic range of land surface dynamics, we used a globally distributed set of eddy-covariance
123 towers that contain (relatively) long periods of data. These in-situ measurements provide the
124 needed meteorological forcing to drive the different schemes and the observed heat flux data
125 required to evaluate the model simulations. Our model assessment and intercomparison exercise is
126 used to address the following research questions: What is the significance of model structure in the
127 performance of Penman-Monteith type models? What is the relative significance of aerodynamic
128 and surface resistances? Which of the model structures and parameterizations are most appropriate
129 for the accurate estimation of evaporation over different landscapes and biome types?

130 **2 Data and Methodology**

131 **2.1 Input Forcing and Evaluation Data**

132 The data used for the development and evaluation of the models in this study comprise of 20
133 globally distributed eddy-covariance towers from the FLUXNET project (Baldocchi et al., 2001). While
134 there are more than 500 towers available from this data archive, a limiting factor on tower selection
135 was the need for soil moisture data for calculations of the surface resistance (see Section 2.3.1). As
136 this variable is not monitored routinely at most tower sites, the capacity for more extensive tower
137 based assessment was significantly reduced. The selected towers are distributed across a range of
138 biome types that include grassland, cropland, shrubland, evergreen needleleaf forest and deciduous
139 broadleaf forest. In each of these biomes, four towers were selected, each with a different canopy
140 height. The period of data across the selected towers varies from 1.5 to 10 years at either hourly or
141 half-hourly time steps, effectively capturing the required variability in canopy development and
142 hydrometeorological conditions. All data were filtered for daytime only measurements, which was
143 defined as when the shortwave downward radiation was greater than 20 W.m^{-2} . This criterion also
144 filters early morning and late afternoon transitions in the atmospheric boundary layer. The data
145 were also filtered for rain events, for frozen periods (when air or land temperature is equal or below

146 zero), for negative turbulent fluxes, for gap-filled records and for low-quality control flags (i.e.
147 quality flag = 0). In total, more than 100 site-years of data (or approximately 500,000 filtered
148 records) were processed for each model formulation. Attributes of the selected towers are listed in
149 Table A1 and a map of the tower locations is provided in Figure 1.

150 **Figure 1**

151 **2.2 Satellite Based Vegetation Data**

152 Phenological characteristics of vegetation, such as the leaf area index and fractional vegetation
153 cover, are required for the parameterization of aerodynamic and surface resistances. As in-situ
154 vegetation data are not generally available at the tower sites, an alternative is to estimate
155 vegetation indices and parameters from remote sensing data. Here, we use remote sensing products
156 from the Moderate-Resolution Imaging Spectroradiometer (MODIS) sensor, which have been
157 employed for this purpose in a number of previous investigations (e.g. Fisher et al., 2008; Mu et al.,
158 2011). We also use a time series of the Normalized Difference Vegetation Index (NDVI) based on the
159 MODIS MOD13Q1 product (Solano et al., 2010) at 250 m spatial resolution and 16 day temporal
160 frequency for the pixel containing each tower. A 3x3 window has been used in other evaporation
161 studies to reduce geo-location errors (Wolfe et al., 2002) and gridding artefacts (Tan et al., 2006)
162 that may present in single-day or 8-day products. While a single pixel is expected to better match the
163 footprint of the eddy-covariance towers, comparison of NDVI derived from a single pixel versus a 3x3
164 window showed a high level of agreement, with an average coefficient of determination (R^2) of 0.96
165 and a root-mean-square difference (RMSD) of 0.03 when averaged across all towers.

166 NDVI time series were obtained from the Simple Object Access Protocol (SOAP) web service of the
167 Oak Ridge National Laboratory (ORNL) MODIS Land Product Subsets (<http://daac.ornl.gov/MODIS/>).
168 Gaps in the NDVI records were filled by a simple linear interpolation between the 16 day retrievals.
169 Given the reliance on satellite data, the tower records coincide with the start of the MODIS record in
170 the year 2000. The gap-filled NDVI time series was converted to leaf area index (LAI) using the

171 methodology developed by Ross (1976), with coefficients from Fisher et al. (2008). The fractional
 172 vegetation cover was calculated using the methodology presented by Jiménez-Muñoz et al. (2009). A
 173 summary of statistics for the fractional vegetation cover and LAI at tower sites is provided in Table
 174 S1 of the Supplementary Materials.

175 **2.3 Description of Penman-Monteith Model Structures**

176 Following is a description of each of the models examined in this analysis, along with the default
 177 resistance schemes that comprise the implemented version of the model. While the model
 178 formulations are described herein, the reader is referred to Appendices B to D and the provided
 179 principal model references for further details.

180 **2.3.1 Single-source Penman-Monteith (PM) model**

181 The Penman model (Penman, 1948) was originally developed for the estimation of the potential
 182 evaporation from open water and saturated land surfaces. To generalize the Penman equation for
 183 water-stressed crops, Monteith (1965) incorporated a canopy resistance term to describe the effect
 184 that partially closed stomata have on evaporation (Inclán and Forkel, 1995). The PM model
 185 conceptualizes the land surface as a so-called “big-leaf”, describing the land surface-atmosphere
 186 exchange via a single bulk stomatal resistance and a single aerodynamic resistance to heat and
 187 vapour. The PM model for estimation of actual evaporation can be formulated as follows (Brutsaert,
 188 2005):

$$\lambda E = \frac{\Delta A + \rho c_p (e^* - e) / r_a}{\Delta + \gamma (1 + \frac{r_s}{r_a})} \quad 1$$

189 where λE is actual evaporation in $\text{W}\cdot\text{m}^{-2}$, λ is the latent heat of vaporization ($2.43 \times 10^6 \text{ J}\cdot\text{kg}^{-1}$),
 190 Δ is the slope of the saturation water vapour pressure curve at an air temperature T_a , ρ is air
 191 density ($\text{m}^3\cdot\text{kg}^{-1}$), γ is the psychrometric constant defined as $\gamma = c_p P_a / (0.622 \lambda)$ with c_p being
 192 specific heat capacity of air ($\text{J}\cdot\text{kg}^{-1}\cdot\text{K}^{-1}$), and P_a is the air pressure in Pa. $e^* - e$ is the vapor pressure

193 deficit, with e^* the saturation vapour pressure and e the actual vapor pressure of the surrounding air
 194 (both in Pa). The aerodynamic and surface resistance parameters (r_a and r_s) are in units of $\text{s}\cdot\text{m}^{-1}$. A is
 195 the available energy, defined as $A = R_n - G_0$ with R_n and G_0 describing the net radiation and
 196 ground heat flux respectively.

197 The aerodynamic resistance formulation used in the standard PM model of this study is that of Thom
 198 (1975) (hereafter Thom's equation):

$$r_a = \frac{1}{\kappa^2 u_a} \left[\ln\left(\frac{z - d_0}{z_{0m}}\right) \ln\left(\frac{z - d_0}{z_{0v}}\right) \right] \quad 2$$

199 where z is measurement height (m), u_a is wind speed ($\text{m}\cdot\text{s}^{-1}$), $\kappa = 0.41$ is von Karman's
 200 constant, d_0 is displacement height and z_{0m} and z_{0v} are the roughness heights for momentum and
 201 water vapor transfer respectively (all in meters). Following Brutsaert (2005), we assume $z_{0v} = z_{0h}$
 202 with z_{0h} being the roughness height for heat transfer. It is common practice to use roughness
 203 parameters (d_0, z_{0m}, z_{0h}) with static values calculated as a fraction of the canopy height (h_c), so
 204 here we employ the equations suggested by Brutsaert (2005):

$$\begin{aligned} d_0 &= 0.66h_c \\ z_{0m} &= 0.1h_c \\ z_{0h} &= 0.01h_c \end{aligned} \quad 3$$

205 For the estimation of the surface resistance, the Jarvis scheme of Jacquemin and Noilhan (1990)
 206 (hereafter Jarvis method) is used (see Appendix B).

207 2.3.2 Two-layer Shuttleworth-Wallace (SW) model

208 The Penman-Monteith model was extended to a two-layer configuration by Shuttleworth and
 209 Wallace (1985) (SW) that included separate canopy and soil layers. The total evaporation in the SW
 210 model is $\lambda E = C_c PM_c + C_s PM_s$, where C_c and C_s are resistance functions for canopy and soil
 211 (respectively). PM_c and PM_s are terms that represent the Penman-Monteith equation applied to full
 212 canopy and to bare soil:

$$PM_c = \frac{\Delta A + \frac{\rho c_p (e^* - e) - \Delta r_a^c A_s}{r_a^a + r_a^c}}{\Delta + \gamma [1 + r_s^c / (r_a^a + r_a^c)]} \quad 4$$

$$PM_s = \frac{\Delta A + \frac{\rho c_p (e^* - e) - \Delta r_a^s (A - A_s)}{r_a^a + r_a^s}}{\Delta + \gamma [1 + r_s^c / (r_a^a + r_a^c)]} \quad 5$$

213 where A is the available energy for the complete canopy ($A = R_n - G_0$) and A_s is the
 214 available energy at the soil surface ($A_s = R_n^s - G_0$). R_n^s is net radiation at the soil surface, which can
 215 be calculated using Beer's law as $R_n^s = R_n \exp(-C \cdot LAI)$, with $C = 0.7$ representing the extinction
 216 coefficient of the vegetation for net radiation. The resistance parameters in the SW model include
 217 bulk canopy resistance (r_s^c), soil surface resistance (r_s^s), aerodynamic resistance between soil and
 218 canopy (r_a^s), canopy bulk boundary layer resistance (r_a^c) and aerodynamic resistance between the
 219 canopy source height and a reference level above the canopy (r_a^a). In application of the SW model,
 220 r_a^a and r_a^s are calculated using the methodology by Shuttleworth and Gurney (1990) (hereafter
 221 SG90). Details of the SW model formulation, as well as the standard parameterization of the
 222 resistances used in this study are detailed in Appendix C.

223 2.3.3 Three-source Mu et al. (2011) (Mu) model

224 The three-source PM model used in this investigation is based on that developed by Mu et al. (2011).
 225 In the Mu model, total evaporation is partitioned into evaporation from the intercepted water in the
 226 wet canopy (λE_{wc}), transpiration from the canopy (λE_t) and evaporation from the soil (λE_s), defined
 227 as $\lambda E = \lambda E_s + \lambda E_t + \lambda E_{wc}$. Evaporation for each source component is derived from the PM
 228 equation and weighted based on fractional vegetation cover (f_c), relative surface wetness (f_w) and
 229 available energy. Parameterization of aerodynamic and surface resistance for each source is based
 230 on biome specific (constant) values of leaf and stomatal conductances for water vapor and sensible
 231 heat transfer, scaled by vegetation phenology and meteorological variables. From a forcing data
 232 perspective, one advantage of the resistance parameterization in the Mu model is that it does not

233 require wind speed and soil moisture data: two variables that are often difficult to prescribe
234 accurately. Specific details of the model formulation are provided in Appendix D.

235 **2.4 Inclusion of a Dynamic Roughness Parameterization**

236 In addition to assuming roughness parameters (d_0, z_{0m}, z_{0h}) as a constant fraction of the canopy
237 height (i.e. static roughness) as detailed above, these variables can also be estimated via a
238 physically-based method. Su et al. (2001) used vegetation phenology, air temperature and wind
239 speed to provide dynamic values of roughness parameters based on the land surface condition.
240 Details of this method are provided in Appendix E.

241 **2.5 Developing Model Parameterization Scenarios**

242 To examine the influence of resistance schemes and model structure on flux simulations, we
243 developed fourteen unique scenarios. Details of these distinct combinations are provided in Table 1.
244 For the default model implementations described above (denoted here as PM^0, SW^0 and Mu^0),
245 parameterizations of the aerodynamic and surface resistances are not modified. For each model
246 type, alternative scenarios are developed to examine the influence of aerodynamic and surface
247 resistance parameterization (see Appendices B to E) and are denoted by superscripts 1, 2, 3, 4 (e.g.
248 PM^1, PM^2). For example, a comparison of PM^0 and PM^1 (see Table 1) illustrates the effect of changing
249 the surface resistance parameterization only, while comparison of PM^0 and PM^2 show the effect of
250 changing the aerodynamic resistance parameterization only (via a change in roughness
251 parameterization). PM^3 and PM^4 show the combined effect of both aerodynamic and surface
252 resistances. In a similar vein for the SW model, comparison of SW^0 and SW^1 isolates the effect of
253 changing the surface resistance parameterization only, while comparison of SW^0 and SW^2 shows the
254 effect of changing the aerodynamic resistance parameterization only. SW^3 and SW^4 are similar to
255 those of PM^3 and PM^4 . For the Mu model, three alternative scenarios are considered to examine the
256 effects of changing aerodynamic resistance (with static and dynamic roughness) and surface

257 resistance. Table S3 in the Supplementary Materials lists the forcing variables that are required to
 258 run each case of the resistance parameterizations.

259 **Table 1: Features of the fourteen model parameterisation combinations for estimating evaporation, where r_s is the**
 260 **surface resistance and r_a is the aerodynamic resistance (see Section 2.3 and Appendices B to D for model and**
 261 **parameterization details).**

Scenario	Model	r_s	r_a	Roughness
PM ⁰	PM	Jarvis	Thom	static
PM ¹	PM	Mu	Thom	static
PM ²	PM	Jarvis	Thom	Dynamic
PM ³	PM	Mu	Thom	Dynamic
PM ⁴	PM	Mu	Mu	N/A
SW ⁰	SW	Jarvis	SG90	static
SW ¹	SW	Mu	SG90	static
SW ²	SW	Jarvis	Thom	Dynamic
SW ³	SW	Mu	Thom	Dynamic
SW ⁴	SW	Mu	Mu	N/A
Mu ⁰	Mu	Mu	Mu	N/A
Mu ¹	Mu	Mu	Thom	Dynamic
Mu ²	Mu	Mu	Thom	static
Mu ³	Mu	Jarvis	Mu	N/A

262

263 2.6 Statistical Evaluation of Model Response

264 We used the R^2 , $RMSD$, the relative error (RE) and the Nash-Sutcliffe efficiency (NSE) coefficient for
 265 statistical evaluation of the model intercomparison and parameterization scenarios. The relative
 266 error is defined as the $RMSD$ normalized by the mean value of the observed evaporation ($\overline{\lambda E_{obs}}$), i.e.
 267 $E = RMSD / \overline{\lambda E_{obs}}$, which is used in a number of similar studies (Su et al., 2005; Kalma et al., 2008).

268 The NSE is a normalized statistic that determines the relative magnitude of the residual variance
 269 (noise) compared to the variance of the measured response (Nash and Sutcliffe, 1970) and defined
 270 as:

$$NSE = 1 - \frac{\left[\sum_{i=1}^n (\lambda E_{i,obs} - \lambda E_{i,sim})^2 \right]}{\left[\sum_{i=1}^n (\lambda E_{i,obs} - \overline{\lambda E_{obs}})^2 \right]} \quad 6$$

271 where $\lambda E_{i,obs}$ is the i th observed λE , $\lambda E_{i,sim}$ is the i th simulated λE and n is the total number
 272 of observations. The NSE coefficient is an indicator of linear fit to the scatterplot of observed versus
 273 simulated data to the 1:1 line. This coefficient has a range between $-\infty$ and 1.0, with an $NSE=1$
 274 indicating an optimal value. Generally, NSE values that are in the range 0 to 1 describe acceptable
 275 modelling performance, whereas negative NSE values indicate poor performance (Moriassi et al.,
 276 2007). The NSE_{avg} , R^2_{avg} and RE_{avg} are used in this paper to represent the average values of the
 277 statistics for multiple towers, and NSE_{std} is used to calculate the standard deviation of NSE for
 278 multiple towers. Hourly or half-hourly filtered data (dependent on the forcing data source) were
 279 used together with the model-simulated responses to calculate these statistical measures.

280 It should be noted that measurement uncertainty in observed tower fluxes is not explicitly included
 281 in these analyses. As such, some caution is required in their interpretation, especially when
 282 evaporation is low and measurement uncertainty might equal the modelling uncertainty.
 283 Furthermore, the issue of non-closure implicit in the eddy-covariance approach (Twine et al., 2000)
 284 can increase the uncertainty in observations. The issue was evaluated in Ershadi et al. (2014)
 285 through examining the energy residual and the Bowen-ratio closure methods using the same towers
 286 employed herein. Ershadi et al. (2014) found that the energy residual closure correction technique
 287 provided better agreement with modelling results and therefore that approach has been adopted
 288 here.

289 **3 Results**

290 Plots of R^2 , RE and NSE for the modelling scenarios are provided in the following sections. Evaluation
 291 of the different scenarios focuses mainly on the NSE of individual towers or on the NSE_{avg} as a
 292 representative value for a biome (see Table 2), as neither the R^2 as a correlation metric nor the RE as

293 a bias error metric are suited as stand-alone measures of scenario performance. For example, a
294 model may show a high R^2 , but with large slope or y-intercept for the linear regression (e.g. Figure S8
295 in the Supplementary Materials). Nevertheless, scatterplots and the statistical metrics are provided
296 for each simulation scenario and each tower site in the Supplementary Materials.

297 **3.1 Penman-Monteith Model**

298 **Influence of r_s parameterization:** The impact of changing the surface resistance scheme from the
299 standard Jarvis method (Equation B1) in PM^0 , to that used in the Mu model (Equation D6) in PM^1 is
300 shown in Figure 2 (the equivalent bar plot can be found in Figure S16 of the Supplementary
301 Materials). A key assumption in the surface resistance parameterization of the Mu model is that the
302 near-surface humidity reflects variations in the soil moisture and hence a humidity-index can be
303 substituted for soil-water stress (Fisher et al., 2008). If this approach can be shown to provide a good
304 representation of the surface resistance, it would remove the reliance on the use of error-prone soil
305 moisture data in calculating this parameter. Based on the NSE , an improved modelling performance
306 is observed for most towers relative to the standard Jarvis method, excluding G1, E2, D1, D2 and D3
307 sites. From PM^0 to PM^1 , the change in NSE_{avg} (i.e. the mean NSE of multiple towers) is positive for
308 grasslands (0.34→0.50), for croplands (0.24→0.53), for shrublands (0.12→0.29) and for evergreen
309 needleleaf forest (0.09→0.21), but negative for deciduous broadleaf forest sites (0.40→0.36).
310 Amongst grassland, cropland, shrubland and evergreen needleleaf forest biomes, the improvement
311 in NSE is more evident for cropland sites, where the range in NSE is increased from 0.07-0.44 to
312 0.42-0.65 and the range in $RMSD$ is reduced from 107-126 $W.m^{-2}$ to 75-103 $W.m^{-2}$ (see Figures S1,
313 S4, S7, S10 and S13 in the Supplementary Materials for statistics). Comparison of PM^2 with PM^3
314 (changing Jarvis r_s to Mu r_s) confirms a similar response of trends in NSE_{avg} across the biomes.

315 **Influence of r_a parameterization:** The influence of dynamic versus static roughness on modelling
316 performance can be tracked in comparisons of two sets of scenarios: PM^2 and PM^0 , and PM^3 and
317 PM^1 . In PM^2 , adjusting the aerodynamic resistance parameterization via the use of dynamic

318 roughness values only improved modelling performance slightly when compared to PM^0 . This
319 improvement (in terms of NSE_{avg}) is more evident for croplands (0.24→0.38) and for deciduous
320 broadleaf forest sites (0.40→0.64). Improvements in NSE_{avg} from PM^0 to PM^2 are smaller for
321 grasslands (0.34→0.40), shrublands (0.12→0.16) and for evergreen needleleaf forest (0.09→0.20).
322 Likewise, comparing PM^3 with PM^1 shows that the NSE at all towers is increased. The results from
323 both sets of scenarios show the positive effect of adding dynamic roughness to the single-source PM
324 model structure.

325 The PM^4 is designed to investigate whether the simple lookup-table based aerodynamic
326 parameterization of the Mu model (equation D11) can be used in the single-source PM model. The
327 benefit of this approach is that the method does not require either roughness parameters or wind
328 speed. Comparison of NSE values of the PM^4 with those of the PM^3 shows that NSE at most towers is
329 decreased in PM^4 , except in deciduous broadleaf forest sites. Therefore, use of the lookup table
330 based approach of Mu for r_a parameterization is not recommended if wind and canopy height data
331 are available. However, comparison of PM^4 and PM^0 shows that in cases where wind, canopy height
332 and soil moisture data are not available, use of the Mu based r_a and r_s parameterizations can
333 increase NSE at most sites, excluding G1, G3, S2 and E2 sites. This is an important result, as these
334 variables are the ones that are most often unavailable in data poor regions.

335 **The best performing PM scenario:** Overall, the PM^3 (which uses Mu r_s and Thom r_a) provides the
336 best performance across most biomes, except over deciduous broadleaf forest sites where PM^2
337 (which uses Jarvis r_s and Thom r_a) presents the best outcome. Both PM^3 and PM^2 utilise Thom's
338 equation with dynamic roughness, which requires reliable wind speed and canopy height data.
339 Results also suggest that the Jarvis method (used in PM^2) is suitable for deciduous broadleaf forest
340 sites, but for other biomes the simpler Mu model resistance (used in PM^3) is more suitable.

341

Figure 2

342 3.2 Shuttleworth-Wallace Model

343 **Influence of r_s parameterization:** Figure 3 and its equivalent bar plot (see Figure S17 in the
344 Supplementary Materials) illustrate variations of R^2 , RE and NSE coefficients for the different SW
345 scenarios. A change in surface resistance from Jarvis to Mu in SW^0 to SW^1 had a limited influence on
346 evaporation estimation over grassland sites (NSE_{avg} remained constant at 0.43), but improved the
347 NSE_{avg} for cropland (0.08→0.36), evergreen needleleaf forest (-0.04→0.08) and deciduous broadleaf
348 forest sites (-0.37→0.17) and decreased it for shrublands (0.07→0.02).

349 The effect of change in r_s parameterization from Jarvis to Mu can also be evaluated by comparing
350 SW^2 and SW^3 (which share Thom r_a with dynamic roughness). The comparison in terms of NSE_{avg}
351 shows a similar trend (as observed for SW^0 to SW^1) for cropland (0.43→0.48) and for evergreen
352 needleleaf forest sites (0.20→0.38), but different trends across grassland (0.44→0.29), shrubland
353 (0.17→0.21) and deciduous broadleaf forest sites (0.65→0.66). The results identify that for the SW
354 model, the influence of r_s parameterization is impacted by the influence of the choice of r_a
355 parameterization. As such, parameterizing resistances for the SW model should be undertaken with
356 care. Overall, a change in surface resistance had less impact on the modelling efficiency of the SW
357 model structure when compared to that observed for the single-source PM model (see Figure 2).

358 **Influence of r_a parameterization:** For aerodynamic resistance, comparisons include evaluating the
359 impact of changes from the SG90 r_a to the Thom r_a with dynamic roughness ($SW^0 \rightarrow SW^2$ and $SW^1 \rightarrow$
360 SW^3), from SG90 r_a to the Mu r_a ($SW^1 \rightarrow SW^4$), and from Thom r_a with dynamic roughness to Mu r_a
361 ($SW^3 \rightarrow SW^4$).

362 Compared to SW^0 , employing Thom's equation with dynamic roughness in SW^2 slightly improved the
363 NSE_{avg} for grasslands (0.43→0.44), considerably increased it for cropland (0.08→0.43), shrubland
364 (0.07→0.17) and evergreen needleleaf forest sites (-0.04→0.20) and dramatically improved it for
365 deciduous broadleaf forest sites (-0.37→0.65). The larger positive response to the changes in r_a

366 parameterization in the cropland and the deciduous broadleaf forest sites can be related to the
367 structure of those canopies. That is, the Thom r_a equation with dynamic roughness is better able to
368 represent the aerodynamic transfer processes when full canopy and soil/understory layers are
369 vertically represented and interact in series as in the SW model structure.

370 For application of the Mu r_a in the SW model, comparison of SW¹ (Mu r_s , SG90 r_a) with SW⁴ (Mu r_s ,
371 Mu r_a) shows that the NSE_{avg} is decreased for grasslands (0.43→0.04) and shrublands (0.02→-0.04),
372 remained constant at 0.36 for croplands, but is significantly increased for evergreen needleleaf
373 forest sites (0.08→0.24) and for deciduous broadleaf forest sites (0.17→0.76). Also, a change of
374 Thom r_a with dynamic roughness in SW³ to Mu r_a in SW⁴ confirms a decrease in NSE_{avg} for a majority
375 of the towers, except for deciduous broadleaf forest sites where it increases (0.66→0.76).

376 Overall, Thom r_a with dynamic roughness (used in SW² and SW³) performed best over grassland,
377 cropland, shrubland and evergreen needleleaf forest sites, while Mu r_a performed best over
378 deciduous broadleaf forest sites.

379 **Influence of using Mu resistance parameterizations:** Comparison of SW⁴ and SW⁰ was designed to
380 identify whether a simpler and less data demanding resistance parameterization (i.e. using both r_s
381 and r_a from the Mu model) can be usefully employed in flux estimation. Results show that such a
382 parameterization is effective in increasing the NSE_{avg} across deciduous broadleaf forest sites
383 (-0.37→0.76), evergreen needleleaf forest sites (-0.04→0.24) and croplands (0.08→0.36). However,
384 the performance is degraded across grasslands (0.43→0.04) and shrublands (0.07→-0.04). As such,
385 the use of the SW⁴ configuration is not advised for grasslands and shrublands.

386 **The best performing SW scenarios:** Amongst the studied biomes, the SW² has the best performance
387 over grasslands (marginal improvement over SW⁰ and SW¹), while SW⁴ has the best performance
388 over deciduous broadleaf forest sites. For other biomes, SW³ is the best option. The use of the Mu
389 surface resistance in SW³ and SW⁴ relaxes the need for soil moisture data. In contrast, the use of the

390 Jarvis surface resistance in SW^2 demands reliable soil moisture data. Also, application of the Mu r_a
391 parameterization for deciduous broadleaf forest sites in SW^4 removes the need for wind and canopy
392 height data. However, accurate wind speed and canopy height data are required for SW^2 and SW^3 ,
393 both of which use Thom r_a .

394

Figure 3

395 3.3 Mu Model

396 **Influence of r_a parameterization:** Figure 4 and its equivalent bar plot (see Figure S18 in the
397 Supplementary Materials) indicate that from Mu^0 to Mu^1 the NSE_{avg} is increased for grassland
398 (0.43→0.47), cropland (0.65→0.67), shrubland (0.10→0.18) and evergreen needleleaf forest sites
399 (0.30→0.35), but is decreased for deciduous broadleaf forest sites (0.71→0.66). As such, Thom r_a
400 with dynamic roughness slightly improves the performance of the model, except over deciduous
401 broadleaf forest sites. Comparison of Mu^0 to Mu^2 (changing Mu r_a to Thom r_a with static roughness)
402 shows a similar response of trends in NSE_{avg} , but smaller in magnitude, across the biomes. These
403 results suggest that the change in aerodynamic resistance in the Mu model has a relatively small
404 influence on the modelling performance, except for deciduous broadleaf forest sites.

405 **Influence of r_s parameterization:** Compared to Mu^0 , which uses the Mu surface resistance,
406 application of the Jarvis surface resistance in the Mu^3 produced lower values of NSE , except for S1,
407 E2 and D1 towers. In particular, the NSE_{avg} is decreased over croplands (0.65→0.50) and evergreen
408 needleleaf forest sites (0.30→0.15). However, change in NSE_{avg} was marginal over deciduous
409 broadleaf forest sites (0.71→0.70). Overall, the use of Mu r_s provides more robust flux estimation
410 than does the use of the Jarvis method over a majority of the studied biomes. Such findings are
411 important in the application of the Mu model in data sparse regions, where accurate soil moisture
412 data are not available.

413 **The best performing Mu scenario:** The Mu^1 scenario has the highest NSE_{avg} over grassland, cropland,
 414 shrubland and evergreen needleleaf forest sites, and the Mu^0 has the highest NSE_{avg} for deciduous
 415 broadleaf forest sites. When accurate wind speed data or roughness parameters are not available,
 416 Mu^0 can be used as a replacement for Mu^1 with a small compromise in estimation efficiency, as the
 417 changes in NSE_{avg} from Mu^0 to Mu^1 were relatively small. Mu^0 also performed better than Mu^3 (Jarvis
 418 r_s , $\text{Mu} r_a$), except over deciduous broadleaf forest sites where the performance was similar.

419 **Figure 4**

420 **Table 2:** NSE_{avg} values of all scenarios over various biomes, with the standard deviation of NSE values shown in
 421 parenthesis. Values in the shaded cells identify the top-ranked scenarios for each biome. Biomes shown in the first
 422 column include grassland (GRA), cropland (CRO), shrubland (SHR), evergreen needleleaf forest (ENF) and deciduous
 423 broadleaf forest (DBF).

Biome	Model	Scenario				
		0	1	2	3	4
GRA	PM	0.34 (0.43)	0.50 (0.23)	0.40 (0.40)	0.53 (0.23)	0.44 (0.22)
	SW	0.43 (0.34)	0.43 (0.34)	0.44 (0.36)	0.29 (0.41)	0.04 (0.50)
	Mu	0.43 (0.29)	0.47 (0.29)	0.46 (0.29)	0.37 (0.29)	(N/A)
CRO	PM	0.24 (0.18)	0.53 (0.12)	0.38 (0.19)	0.57 (0.12)	0.55 (0.12)
	SW	0.08 (0.36)	0.36 (0.25)	0.43 (0.18)	0.48 (0.23)	0.36 (0.29)
	Mu	0.65 (0.13)	0.67 (0.11)	0.64 (0.11)	0.50 (0.09)	(N/A)
SHR	PM	0.12 (0.07)	0.29 (0.12)	0.16 (0.10)	0.35 (0.15)	0.19 (0.10)
	SW	0.07 (0.03)	0.02 (0.25)	0.17 (0.10)	0.21 (0.35)	-0.04 (0.21)
	Mu	0.10 (0.08)	0.18 (0.14)	0.15 (0.11)	0.04 (0.03)	(N/A)
ENF	PM	0.09 (0.18)	0.21 (0.19)	0.20 (0.19)	0.29 (0.23)	0.19 (0.19)
	SW	-0.04 (0.20)	0.08 (0.19)	0.20 (0.19)	0.38 (0.19)	0.24 (0.16)
	Mu	0.30 (0.25)	0.35 (0.27)	0.31 (0.26)	0.15 (0.19)	(N/A)
DBF	PM	0.40 (0.15)	0.36 (0.10)	0.64 (0.06)	0.52 (0.11)	0.60 (0.10)
	SW	-0.37 (0.54)	0.17 (0.15)	0.65 (0.06)	0.66 (0.08)	0.76 (0.05)
	Mu	0.71 (0.09)	0.66 (0.10)	0.54 (0.11)	0.70 (0.07)	(N/A)

424

425 3.4 Identification of the Best Performing Models and Parameterizations

426 To develop an overall understanding on the performance of the reviewed scenarios, the NSE_{avg} and
427 NSE_{std} of each scenario for each biome were calculated (see Table 2). From this table it can be seen
428 that the best performing scenario for grassland and shrubland sites is PM^3 , for croplands it is Mu^1 ,
429 for evergreen needleleaf forest sites it is SW^3 and for deciduous broadleaf forest sites it is SW^4 . In all
430 of these scenarios (PM^3 , Mu^1 , SW^3 , SW^4) the surface resistance is based on the Mu method, which
431 requires no soil moisture data. Of the selected top performing scenarios, the Mu r_a method is only
432 used in SW^4 (best performing in the deciduous broadleaf forest sites). However, in the PM^3 , SW^3 and
433 Mu^1 scenarios the aerodynamic resistance is calculated using Thom's equation with dynamic
434 roughness, which requires reliable wind and canopy height data. As these forcing data are not
435 always available for large-scale applications, an important question is to determine whether the
436 scenarios that use Mu r_a over grassland, cropland, shrubland and evergreen needleleaf forest sites
437 can produce NSE_{avg} values close to the top performing model?

438 To answer this, inspection of the NSE_{avg} and NSE_{std} values in Table 2 shows that for croplands, Mu^0
439 satisfies the above constraint (0.65 compared to 0.67 for the top model). However, for grassland
440 sites the next best scenario is PM^1 ($NSE_{avg} = 0.50$), which relies on the Thom r_a formulation. Likewise,
441 no highly ranked alternative scenario can be found for the shrubland and evergreen needleleaf
442 forest sites. As such, there are no alternative candidate scenarios for grassland, shrubland and
443 evergreen needleleaf forest biomes that produce NSE_{avg} values comparable to those realized from
444 the top-performing scenarios (see Table 2) by substituting the Mu r_a in the models.

445 4 Discussion

446 In the present study, fourteen different scenarios were constructed to examine how changes in the
447 default resistance parameterizations of a single-source, a two-layer and a three-source PM type
448 model might influence their performance in the reproduction of actual evaporation.

449 Intercomparison of these scenarios provided insights into the influence of both model structure and
450 parameterizations.

451 **4.1 Impact of Changes in Model Structure**

452 **Influence of r_a parameterization:** The aerodynamic resistance played a relatively minor role in flux
453 estimation for the PM model, in accord with the findings of Bailey and Davies (1981) and Irmak and
454 Mutiibwa (2010). Likewise, changes in the aerodynamic resistance in the Mu scenarios produced
455 only minor improvements in model performance. In contrast, parameterization of the aerodynamic
456 resistance had a major influence on the performance of the SW scenarios. Comparison of the various
457 r_a schemes in the PM, SW and Mu models indicated that while the Thom r_a with dynamic roughness,
458 which requires wind speed and canopy height data, increased the NSE_{avg} over a majority of the
459 studied biomes, the performance advantage relative to using the Mu r_a was generally marginal for
460 the PM and Mu models. Where wind speed and canopy height data are available, Thom r_a with
461 dynamic roughness is recommended for the SW model, except over the deciduous broadleaf forest
462 biome.

463 **Influence of r_s parameterization:** Analysis of the scenarios illustrated that the surface resistance
464 parameterization significantly affects model performance in the PM and Mu models, while the SW
465 models showed variable responses. For the PM scenarios, the Mu r_s increased the overall
466 performance (i.e. NSE_{avg}) in croplands, and to a lesser extent in shrubland, evergreen needleleaf
467 forest and in grassland sites. However, it did not improve the results in the deciduous broadleaf
468 forest sites. The response of the Mu model to a change in surface resistance parameterization was
469 somewhat different. In the Mu scenarios, the default r_s parameterization performed better than
470 that of the Jarvis method, except over deciduous broadleaf forest sites where the performance
471 change was marginal. Nevertheless, pre-calibration of Mu r_s might have contributed in the increased
472 efficiency of the scenarios that employ those parameters, especially as 11 towers that were used in
473 the current study overlap with those in the Mu et al. (2011) study.

474 **The top-ranked model and parameterizations:** Overall, the top-ranked scenarios (see Table 2) for
475 each biome were: PM³ for grasslands (0.53) and shrublands (0.35), Mu¹ for croplands (0.67), SW³ for
476 evergreen needleleaf forest (0.38) and SW⁴ for deciduous broadleaf forest sites (0.76) (NSE_{avg} shown
477 in parenthesis). These results highlight the role of model structure in evaporation modelling, as the
478 single source PM model provided better results over short canopies (grasslands and shrublands) and
479 the two-layer structure of the SW model provided better results over forest biomes. Interestingly,
480 the three-source Mu model structure provided an exception here, as it performed the best when
481 applied over croplands (which have relatively short canopies).

482 The common element of the top-ranked scenarios is the use of the Mu surface resistance. Likewise,
483 PM³, SW³ and Mu¹ all use the Thom aerodynamic resistance with dynamic roughness, while SW⁴
484 uses the Mu r_a . The Mu model itself showed low sensitivity to r_a parameterization, while its r_s
485 parameterization improved other models.

486 **Comparison with alternative process-based evaporation models:** The Penman-Monteith model
487 variants of the current study showed variable performances in evaporation estimation across the
488 different studied biomes, even when considering the top-ranked configurations. In comparison, a
489 number of alternative process-based models have shown superior performance in related studies.
490 Recently, Ershadi et al. (2014) compared four process-based evaporation models that included the
491 Surface Energy Balance System (SEBS) (Su, 2002), PT-JPL (Fisher et al., 2008), Advection-Aridity
492 (Brutsaert and Stricker, 1979) and a single-source PM model with Jarvis r_s and Thom r_a with dynamic
493 roughness (i.e. similar to PM²). Using the same dataset of the current study, they found that an
494 ensemble of model responses had the best performance, followed by the PT-JPL and SEBS. The issue
495 of appropriate model selection is obviously a key consideration that will ultimately be guided by user
496 experience, data needs and data availability. Nevertheless, adopting a multi-model strategy for flux
497 estimation seems a useful approach in understanding and constraining the uncertainties that
498 emerge from model structure and parameterization configurations.

499 4.2 Issues of Data Uncertainty

500 As discussed above, a consideration in the choice of both the model and parameterization scheme is
501 the availability of reliable data. Application of the surface resistance method of the Mu model is
502 important in relaxing the need for soil moisture data and is likely to facilitate its application in
503 evaporation estimation from field to larger scales (Mu et al., 2012). Similar results were found in
504 previous work using a modified Priestly-Taylor model (PT-JPL model; Fisher et al., 2008). Like the Mu
505 model, the PT-JPL approach does not require wind speed or soil moisture data, and recent
506 comparisons against more complex models illustrated that the PT-JPL performs well (Vinukollu et al.,
507 2011; Ershadi et al., 2014).

508 The aerodynamic resistance scheme used by the top-ranked scenarios examined here (except for
509 deciduous broadleaf forest sites) were all based on Thom r_a with dynamic roughness, which requires
510 reliable wind speed and canopy height data. Generally, accurate in-situ based wind speed data are
511 not routinely available for many study sites. Likewise, the only source for canopy height at the global
512 scale is a static product developed by NASA-JPL (Simard et al., 2011), which has limited capability
513 over short vegetation (e.g. grasslands and croplands). Although the Mu model is designed for large
514 scale applications with coarse spatial (1 km) and temporal (8 day to yearly) resolutions, the results of
515 the current study show that in the absence of required forcing data the Mu resistance scheme could
516 be used at the tower scale with reasonable performance.

517 Part of the deficiencies in model performance, especially over shrubland sites ($NSE_{avg} < 0.34$) is likely
518 related to the spatio-temporal resolution (i.e. 250 m, 16 days) of the MODIS data. MODIS data are
519 used in the estimation of vegetation indices, which are subsequently used for parameterization of
520 aerodynamic and surface resistances. Shrubland sites display considerable land surface
521 heterogeneity and the contrasting bare soil and vegetation elements may not be well captured at
522 the coarse remote sensing pixels (Stott et al., 1998; Montandon and Small, 2008). A difference
523 between the results of this and previous studies that have reported higher performance of PM type

524 models, may reflect the inherent uncertainties introduced via the input data, since the majority of
525 prior investigations were performed with detailed field observations of vegetation characteristics
526 (Huntingford et al., 1995; Li et al., 2011). Clearly there is a need for high-quality in-situ phenological
527 descriptions to undertake the types of globally distributed analysis performed here, but
528 unfortunately they are often lacking. Likewise, a better understanding of the inherent scale issues in
529 flux estimation is required, particularly for the impact of both spatial and temporal scaling on the
530 performance of aerodynamic and surface resistance terms (McCabe and Wood, 2006; Ershadi et al.,
531 2013).

532 **5 Conclusion**

533 The influence of model structure and resistance parameterization is an important, but often
534 overlooked, consideration in the performance of Penman-Monteith type evaporation models.
535 Understanding the effects of model structure and parameterization configurations is non-trivial due
536 to the mixed influence of data uncertainty, hydrometeorological variability and the complexity of the
537 modelling system (Raupach and Finnigan, 1988). In this study, the effects of model structure and
538 choice of resistance parameterization were investigated using three Penman-Monteith type models.
539 The structure of the models varied from single-source, to two-layer and three-source. To examine
540 the influence of model parameterization, a number of commonly used resistance schemes were
541 substituted into the models, with flux estimates evaluated against locally measured evaporation at a
542 number of eddy-covariance tower sites.

543 Results illustrated the considerable variability in model performance over the different biomes, with
544 no single model structure or scenario providing a consistently top-ranked result over the twenty
545 study sites. Indeed, the top-ranked scenarios highlighted the importance of model structure. Except
546 over croplands, where the three-source Mu model structure performed the best, the single-source
547 PM structure performed better over short canopies while the two-layer SW structure performed

548 better over forest canopies. Changes in resistance parameterizations, in particular the surface
549 resistance, were also seen to strongly influence the performance of the models.

550 A key consideration from the findings of this work relates to the application of Penman-Monteith
551 type models across a range of hydrological and related disciplines. Penman-Monteith type
552 approaches have been used with modifications in structure and parameterizations in a number of
553 global scale datasets (Zhang et al., 2010), global circulation models (Dolman, 1993) and land surface
554 model applications. Hence, uncertainties and errors originating from non-optimum structure or
555 parameterization of the models can significantly influence the accuracy of simulation results,
556 evaluation of global trends (Jiménez et al., 2011; Mueller et al., 2013) and decisions based on such
557 results, including but not limited to drought (Sheffield and Wood, 2008), land-atmosphere
558 interactions (Seneviratne et al., 2006) and climate change projections (Droogers et al., 2012).

559 As the focus of this paper was on reporting biome-level efficiency of model and parameterization
560 configurations, the influence of vegetation phenology (e.g. LAI, fractional vegetation cover), land
561 cover and climate zone were not explicitly considered in the analysis. Future work is needed to focus
562 on site-level evaluation of the models to address these important issues. Furthermore, given that
563 the top-ranked scenarios identified in this study varied across different biomes, an ensemble model
564 based assessment might be an appropriate approach for global flux estimation (Jiménez et al., 2011;
565 Mueller et al., 2011; Mueller et al., 2013). Alternatively, a biome-specific tiled evaporation product
566 could also be developed by using the best model and parameterization configuration for each biome
567 type. In either case, further understanding the role of parameterization on model performance is
568 critical in assessing the impact of choice on derived products.

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589 menu/modis_webservice.html)

590

591 **Appendix A: Details of the Selected Eddy-Covariance Towers**

592 **Table A1: Selected eddy-covariance towers and their characteristics (Ershadi et al., 2014). z_g is the site elevation (above**
 593 **sea level) in m, z_m is tower height in m, h_c is the canopy height in m, Y is the number of years of data and L is the**
 594 **processing level of data. Abbreviations for climate types are defined for Sub-Tropical Mediterranean (STM), Temperate**
 595 **Continental (TC), Temperate (TEM) and Tropical (TRO).**

	ID	Name	Country	Climate	Lat.	Lon.	z_g	z_m	h_c	Y	L	Reference
		Grasslands										
G1	PT-Mi2	Mitra IV Tojal	Portugal	STM	38.5	-8.0	190	2.5	0.05	2	3	(Gilmanov et al., 2007)
G2	US-Aud	Audubon Research Ranch	USA	Dry	31.6	-110.5	1469	4	0.15	4	3	(Krishnan et al., 2012)
G3	US-Goo	Goodwin Creek	USA	STM	34.3	-89.9	87	4	0.3	4	3	(Hollinger et al., 2010)
G4	US-Fpe	Fort Peck	USA	Dry	48.3	-105.1	634	3.5	0.3	4	3	(Horn and Schulz, 2011)
		Croplands										
C1	US-ARM	ARM SGP – Lamont	USA	STM	36.6	-97.5	314	60	0.5	4	3	(Lokupitiya et al., 2009)
C2	US-Ne3	Mead – rainfed	USA	TC	41.2	-96.4	363	6	2.5	10	3	(Richardson et al., 2006)
C3	US-Ne1	Mead – irrigated	USA	TC	41.2	-96.5	361	6	3	10	3	(Richardson et al., 2006)
C4	US-Bo1	Bondville	USA	TC	40.0	-88.3	219	10	3	7	3	(Hollinger et al., 2010)
		Shrubland/Woody Savannah										
S1	US-SRc	Santa Rita Creosote	USA	Dry	31.9	-110.8	991	4.25	1.7	1.5	2	(Cavanaugh et al., 2011)
S2	US-SRM	Santa Rita Mesquite	USA	Dry	31.8	-110.9	1116	6.4	2.5	7	2	(Scott et al., 2009)
S3	BW-Ma1	Maun- Mopane Woodland	Botswana	Dry	-19.9	23.6	950	13.5	8	2	3	(Veenendaal et al., 2004)
S4	AU-How	Howard Springs	Australia	TRO	-12.5	131.2	38	23	15	5	3	(Hutley et al., 2005)
		Evergreen Needleleaf Forest										
E1	NL-Loo	Loobos	Netherlands	TEM	52.2	5.7	25	52	15.9	5	3	(Sulkava et al., 2011)
E2	US-Fuf	Flagstaff - Unmanaged Forest	USA	TC	35.1	-111.8	2180	23	18	6	2	(Román et al., 2009)
E3	DE-Tha	Anchor St. Tharandt - old spruce	Germany	TEM	51.0	13.6	380	42	30	2	3	(Delpierre et al., 2009)
E4	US-Wrc	Wind River Crane Site	USA	TEM	45.8	-122.0	371	85	56.3	9	2	(Wharton et al., 2009)
		Deciduous Broadleaf Forest										
D1	US-MOz	Missouri Ozark Site	USA	STM	38.7	-92.2	219	30	24.2	5	2	(Hollinger et al., 2010)
D2	US-WCr	Willow Creek	USA	TC	45.8	-90.1	520	30	24.3	5	3	(Curtis et al., 2002)
D3	US-MMS	Morgan Monroe State Forest	USA	STM	39.3	-86.4	275	48	27	6	2	(Dragoni et al., 2011)
D4	DE-Hai	Hainich	Germany	TEM	51.1	10.5	430	43.5	33	3	3	(Rebmann et al., 2005)

596 **Appendix B: Jarvis Surface Resistance Parameterization Method**

597

598 The Jarvis method for estimation of surface resistance (r_s) can be expressed as:

$$r_s = \frac{r_s^{min}}{LAI \times F_1 \times F_2 \times F_3 \times F_4} \quad \text{B1}$$

599 Where r_s^{min} is the minimum canopy resistance (s.m^{-1}), LAI is the leaf area index ($\text{m}^2.\text{m}^{-2}$)

600 and F_1, F_2, F_3 and F_4 are weighting functions representing the effects of solar radiation, humidity,

601 soil moisture and air temperature on plant stress. Following Chen and Dudhia (2001), the weighting

602 functions for Jarvis method type surface resistance are defined as following:

$$F_1 = \frac{r_s^{min}/r_s^{max}+f}{1+f} \text{ with } f = 0.55 \frac{R_g}{R_{gl}} \left(\frac{2}{LAI} \right)$$

$$F_2 = \frac{1}{1 + h_s(q^* - q)}$$

B2

$$F_3 = 1 - 0.0016(T_{ref} - T_a)^2$$

$$F_4 = \sum_{i=1}^{N_{root}} \frac{(\theta_i - \theta_{wilt})d_i}{(\theta_{ref} - \theta_{wilt})d_t}$$

603 where r_s^{max} is the maximum canopy resistance (s.m^{-1}), R_{gl} is the minimum solar radiation

604 necessary for transpiration (W.m^{-2}), R_g is the incident solar radiation (W.m^{-2}), h_s is a parameter

605 associated with the water vapor deficit, $q^* - q$ represents the water vapour deficit (kg.kg^{-1}), q^* is

606 saturation specific humidity, q is actual specific humidity, T_{ref} is the optimal temperature for

607 photosynthesis (K) and T_a is the air temperature (K). d_i is the thickness of the i th soil layer (m), d_t is

608 the total thickness of the soil layer (m) and N_{root} is the number of soil layers. In this study, the

609 observation depth of the soil moisture sensor(s) (5 to 10 cm) is considered to be representative of

610 the overall soil column. Obviously, there is potential for rapid changes in the observed near-surface

611 soil moisture (as a response to precipitation) which may not accurately reflect the deeper soil

612 column response, especially for sites with deeply rooted system. However, as there is limited

613 availability of soil moisture data with which to refine the technique, we employ this relatively simple
614 scheme as a compromise. The G1, S3, S4, E1, E3 and D4 towers (see Table A1) had one soil layer,
615 and the rest of towers had two soil layers included in the analysis. Values of r_s^{min} , r_s^{max} , R_{gl} , h_s and
616 T_{ref} were based on the vegetation lookup tables used in the NOAH land surface model (see Kumar
617 et al., 2011).

618 Soil moisture content thresholds for field capacity (θ_{ref}) and wilting point (θ_{wilt}) provide
619 characteristics of the soil type. As soil type information is not available for all sites from field
620 investigations and the values in existing global soil databases are not reliable at the point scale, long-
621 term surface layer soil moisture observations from each tower are used to determine soil moisture
622 thresholds (Calvet et al., 1998; Zotarelli et al., 2010). To do this, the field capacity is determined as
623 the 99th percentile of the “after rain” soil moisture records of the tower. The estimated θ_{ref} is
624 constrained by the maximum value of θ_{ref} in the NOAH soil table, as the length of soil moisture data
625 might not be sufficient to result a realistic θ_{ref} . Similarly, the wilting point threshold is determined
626 from the 1st percentile of the soil moisture records, but capped to the minimum value of θ_{wilt} in the
627 NOAH soil table. Both vegetation and soil parameter tables of the NOAH model can be obtained
628 from <http://www.ral.ucar.edu/research/land/technology/lsm.php>.

629

630 **Appendix C: Shuttleworth-Wallace Model**

631

632 In the SW model, C_c and C_s are resistance functions for canopy and soil (respectively) and
633 are given by the following equations:

$$C_c = \left[1 + \frac{R_c R_a}{R_s (R_c + R_a)} \right]^{-1} \quad \text{c1}$$

$$C_s = \left[1 + \frac{R_s R_a}{R_c (R_s + R_a)} \right]^{-1} \quad \text{c2}$$

634 where

$$R_a = (\Delta + \gamma) r_a^a \quad \text{c3}$$

635 The bulk stomatal resistance of the canopy (r_s^c) is a surface resistance, which is influenced by
636 the surface area of the vegetation. In the original derivation of the SW model, the bulk stomatal
637 resistance was calculated by upscaling the leaf scale stomatal resistance (r_{ST}) based on the leaf area
638 index (LAI) as $r_s^c = r_{ST}/2 \times LAI$, with r_{ST} assumed as a constant value or calibrated based on
639 evaporation observations. However, we derive the bulk canopy resistance using the Jarvis method of
640 Noilhan and Planton (1989) (see Appendix B), as is used in a number of previous studies of the
641 Shuttleworth-Wallace model (e.g. Zhou et al., 2006; Irmak, 2011). The soil surface resistance (r_s^s) is
642 derived from the above mentioned Jarvis method, using the “Barren and Sparsely Vegetated”
643 category of the NOAH vegetation table for the bare soil.

644 Three aerodynamic resistances appear in the SW model: an aerodynamic resistance between the
645 soil/substrate surface and the canopy source height (r_a^s), a bulk boundary layer resistance of
646 vegetative elements in the canopy (r_a^c), and an aerodynamic resistance between the canopy source
647 height and a reference level above the canopy (r_a^a). The bulk boundary layer resistance (r_a^c) is
648 calculated by scaling the leaf scale mean boundary layer resistance r_b to the canopy scale using LAI ,
649 as $r_a^c = r_b/2 \times LAI$, with r_b considered constant at $25 \text{ s}\cdot\text{m}^{-1}$ (Shuttleworth and Wallace, 1985).

650 However, r_a^a and r_a^s are calculated using the following equations (Shuttleworth and Gurney, 1990)

651 (i.e. SG90):

$$r_a^a = \frac{1}{\kappa u_*} \ln \left(\frac{z - d_0}{h_c - d_0} \right) + \frac{h_c}{n K_h} \left\{ \exp \left[n \left(1 - \frac{z_{0m} + d_0}{h_c} \right) \right] - 1 \right\} \quad C4$$

$$r_a^s = \frac{h_c \exp(n)}{n K_h} \left\{ \exp \left(-\frac{n z'_{0m}}{h_c} \right) - \exp \left[-n \left(\frac{z_{0m} + d_0}{h_c} \right) \right] \right\} \quad C5$$

652 where z'_{0m} is the roughness length of bare soil surface (=0.01 m) (van Bavel and Hillel, 1976)

653 and n is the eddy diffusivity decay constant (dimensionless), which is assumed fixed at 2.5 for

654 agricultural crops by Shuttleworth and Wallace (1985). However, following Zhang et al. (2008) and

655 based on the values given by Brutsaert (1982), we assume $n = 2.5$ when $h_c < 1$ m and $n = 4.25$

656 when $h_c > 10$ m. For the cases where $1 \geq h_c \geq 10$, a linear interpolation is applied as $n =$

657 $0.1944h_c + 2.3056$. The eddy diffusion coefficient at the top of canopy (K_h in $\text{m}^2 \cdot \text{s}^{-1}$) is calculated as

658 $K_h = \kappa u_* (h_c - d_0)$, with the friction velocity (u_* in $\text{m} \cdot \text{s}^{-1}$) calculated as $u_* = \kappa u_a / \ln[(z - d_0) /$

659 $z_{0m}]$. As is common in general applications of the SW model, the roughness variables d_0 and z_{0m}

660 are assumed as a fraction of the canopy height (Brutsaert, 2005), as in Equation 3.

661

662 **Appendix D: Mu Model Evaporation Component and Resistances**

663 **D1. Evaporation from Wet Canopy**

664 Evaporation from a wet canopy (i.e. intercepted water) is calculated using the following equation:

$$\lambda E_{wc} = f_w \frac{\Delta A_c + f_c \rho c_p (e^* - e) / r_a^{wc}}{\Delta + \gamma \frac{r_s^{wc}}{r_a^{wc}}} \quad \text{D1}$$

665 where f_c is fractional vegetation cover. f_w is the relative surface wetness and calculated as

666 $f_w = RH^4$, which is based on the concept originally developed by Fisher et al. (2008). In the original

667 Mu model, daily average values of RH were used and f_w was assumed zero when daily average

668 $RH < 0.7$. However, here we used hourly (or half-hourly) data and did not filter f_w based on low RH

669 values.

670 The aerodynamic resistance r_a^{wc} and surface resistance r_s^{wc} for wet canopy are defined as:

$$r_a^{wc} = \frac{r_h^{wc} r_r^{wc}}{r_h^{wc} + r_r^{wc}} \quad \text{D2}$$

$$r_s^{wc} = \frac{1}{f_w g_e LAI} \quad \text{D3}$$

671 where r_h^{wc} is wet canopy resistance to sensible heat transfer and r_r^{wc} is the wet canopy

672 resistance to radiative heat transfer, which are formulated as following:

$$r_h^{wc} = \frac{1}{f_w g_h LAI} \quad \text{D4}$$

$$r_r^{wc} = \frac{\rho c_p}{4\sigma T_a^3}$$

673 g_e and g_h are leaf conductance to evaporated water vapor and sensible heat (respectively) per unit

674 LAI , T_a is air temperature ($^{\circ}\text{C}$) and σ is the Stefan-Boltzmann constant. Based on Mu et al. (2011), g_e

675 and g_h are assumed similar and constant for each biome as listed in Table B1. The available energy

676 for crop and soil is partitioned based on the fractional vegetation cover (f_c) as $A_s = f_c R_n$ and

677 $A_s = (1 - f_c)R_n - G_0.$

678 D2. Canopy Transpiration

679 The canopy transpiration λE_t is calculated as:

$$\lambda E_t = (1 - f_w) \frac{\Delta A_c + f_c \rho c_p (e^* - e) / r_a^t}{\Delta + \gamma \left(1 + \frac{r_s^t}{r_a^t}\right)} \quad \text{D5}$$

680 Where r_a^t and r_s^t are aerodynamic and surface resistances for transpiration, respectively.

681 The bulk canopy resistance (r_s^t) is the inverse of the bulk canopy conductance (C_c) and calculated as:

$$r_s^t = \frac{1}{C_c} \quad \text{D6}$$

682 The assumption here is that the stomatal conductance (G_s^{st}) and cuticular conductance (G_s^{cu}) are in

683 parallel, but both are in series with the canopy boundary-layer conductance G_s^b . Therefore, the

684 canopy conductance to transpiration is calculated as:

$$C_c = \begin{cases} (1 - f_w) \frac{(G_s^{st} + G_s^{cu}) G_s^b}{G_s^{st} + G_s^{cu} + G_s^b} LAI & , LAI > 0, (1 - f_w) > 0 \\ 0 & , LAI = 0, (1 - f_w) = 0 \end{cases} \quad \text{D7}$$

685 Where $G_s^b = g_h$, $G_s^{cu} = r_{corr} g_{cu}$ and $G_s^{st} = c_L m(T_{min}) m(VPD) r_{corr}$ with VPD being the

686 vapor pressure deficit (Pa). The leaf cuticular conductance (g_{cu}) is per unit LAI, and assumed equal

687 to $0.00001 \text{ m} \cdot \text{s}^{-1}$ for all biomes. Also, the mean potential stomatal conductance (c_L) is per unit leaf

688 area, and is assumed constant for each biome (Table B1). The r_{corr} is the correction factor for G_s^{st} to

689 adjust it based on the standard air temperature and pressure (20 °C and 101,300 Pa) using the

690 following equation:

$$r_{corr} = \frac{1}{\frac{101300}{Pa} \left(\frac{T_a + 273.15}{293.15} \right)^{1.75}} \quad \text{D8}$$

691 $m(T_{min})$ is a multiplier that limits potential stomatal conductance by minimum air temperature
 692 (T_{min}), and $m(VPD)$ is a multiplier used to reduce the potential stomatal conductance when
 693 $VPD = e^* - e$ is high enough to reduce canopy conductance. Following Mu et al. (2007), $m(T_{min})$
 694 and $m(VPD)$ are calculated as following:

$$m(T_{min}) = \begin{cases} 1 & T_{min} \geq T_{min}^{open} \\ \frac{T_{min} - T_{min}^{close}}{T_{min}^{open} - T_{min}^{close}} & T_{min}^{close} < T_{min} < T_{min}^{open} \\ 0 & T_{min} \leq T_{min}^{close} \end{cases} \quad \text{D9}$$

$$m(VPD) = \begin{cases} 1 & VPD \leq VPD_{open} \\ \frac{VPD_{close} - VPD}{VPD_{close} - VPD_{open}} & VPD_{open} < VPD < VPD_{close} \\ 0 & VPD \geq VPD_{close} \end{cases} \quad \text{D10}$$

695 Values of T_{min}^{open} , T_{min}^{close} , VPD_{open} and VPD_{close} are listed in Table B1 for each biome type. Also, the
 696 aerodynamic resistance to canopy transpiration, r_a^t , is calculated based on the convective heat
 697 transfer resistance r_h and radiative heat transfer resistance r_r , assuming they are in parallel using
 698 the following equation (Thornton, 1998):

$$r_a^t = \frac{r_h^t r_r^t}{r_h^t + r_r^t} \quad \text{D11}$$

699 Where $r_h^t = 1/g_{bl}$ and $r_r^t = r_r^{wc}$ with g_{bl} being the leaf-scale boundary layer conductance
 700 per unit LAI and assumed equal to that of the sensible heat (i.e. $g_{bl} = g_h$).

701 D3. Soil Evaporation

702 Evaporation from the soil surface is calculated as the sum of evaporation from wet soil (λE_{ws}) and
 703 evaporation from saturated soil (λE_{ss}), such that:

$$\lambda E_s = \lambda E_{ws} + \lambda E_{ss}. \quad \text{D12}$$

704 Partitioning of the soil surface to wet and saturated components is based on the relative surface
 705 wetness f_w , with the evaporation from the wet soil calculated as:

$$\lambda E_{ws} = f_w \frac{\Delta A_s + (1 - f_c) \rho c_p (e^* - e) / r_a^s}{\Delta + \gamma \frac{r_s^s}{r_a^s}} \quad \text{D13}$$

706 Similarly, evaporation from the saturated soil is calculated as:

$$\lambda E_{ss} = RH^{VPD/\beta} (1 - f_w) \frac{\Delta A_s + (1 - f_c) \rho c_p (e^* - e) / r_a^s}{\Delta + \gamma \frac{r_s^s}{r_a^s}}$$

707 where r_a^s and r_s^s are aerodynamic and surface resistances for the soil surface. $RH^{VPD/\beta}$ is a
 708 soil moisture constraint that is used following Fisher et al. (2008). This function is based on the
 709 complementary hypothesis and describes land-atmosphere interactions via the air vapour pressure
 710 deficit VPD and relative humidity RH , with β assigned a constant value of 200. The soil surface
 711 resistance r_s^s is calculated as:

$$r_s^s = r_{corr} r_{totc} \quad \text{D14}$$

712 where r_{totc} is a function of VPD and biological parameters r_{bl}^{min} and r_{bl}^{max} as follows:

$$r_{totc} = \begin{cases} r_{bl}^{max} & VPD \leq VPD_{open} \\ r_{bl}^{max} - \frac{(r_{bl}^{max} - r_{bl}^{min}) \times (VPD_{close} - VPD)}{VPD_{close} - VPD_{open}} & VPD_{open} < VPD < VPD_{close} \\ r_{bl}^{min} & VPD \geq VPD_{close} \end{cases} \quad \text{D15}$$

713 VPD_{open} is the VPD when there is no water stress on transpiration and VPD_{close} is the VPD when
 714 water stress causes stomata to close almost completely, halting plant transpiration. Values for r_{bl}^{max} ,
 715 r_{bl}^{min} , VPD_{open} and VPD_{close} are listed in Table B1.

716 The aerodynamic resistance at the soil surface (r_a^s) is parallel to both the resistance to convective
 717 heat transfer (r_h^s) and the resistance to radiative heat transfer r_r^s , with its components calculated as:

$$r_a^s = \frac{r_h^s r_r^s}{r_h^s + r_r^s} \quad \text{D16}$$

718 Where $r_r^s = r_r^{wc}$ and $r_h^s = r_h^s$.

719 Table 2 shows the Biome-Property-Lookup-Table (BPLT) used in the Mu model. As explained by Mu
 720 et al. (2011), VPD and T_{min} parameters were derived from calibrations performed by Zhao et al.
 721 (2005), but other parameters were calibrated based on biome aggregated observed evaporation and
 722 Gross Primary Production (GPP) values at 46 AmeriFlux tower sites, some of which are included in
 723 the current study.

724 **Table B1: The Biome-Property-Lookup-Table (BPLT) adopted from Mu et al. (2011). Land covers are defined as evergreen**
 725 **needleleaf forest (ENF), evergreen broadleaf forest (EBF), deciduous needleleaf forest (DNF), deciduous broadleaf forest**
 726 **(DBF), mixed forest (MF), woody savannahs (WL), savannahs (SV), closed shrubland (CSH), open shrubland (OSH) and**
 727 **cropland (CRO). GRA class is for grassland, urban and built-up, and barren or sparsely vegetated biomes, collectively.**

Crop	ENF	EBF	DNF	DBF	MF	CSH	OSH	WL	SV	GRA	CRO
T_{min}^{open} (°C)	8.31	9.09	10.44	9.94	9.5	8.61	8.8	11.39	11.39	12.02	12.02
T_{min}^{close} (°C)	-8	-8	-8	-6	-7	-8	-8	-8	-8	-8	-8
VPD_{close} (Pa)	3000	4000	3500	2900	2900	4300	4400	3500	3600	4200	4500
VPD_{open} (Pa)	650	1000	650	650	650	650	650	650	650	650	650
g_h ($m.s^{-1}$)	0.04	0.01	0.04	0.01	0.04	0.04	0.04	0.08	0.08	0.02	0.02
g_e ($m.s^{-1}$)	0.04	0.01	0.04	0.01	0.04	0.04	0.04	0.08	0.08	0.02	0.02
c_L ($m.s^{-1}$)	0.0032	0.0025	0.0032	0.0028	0.0025	0.0065	0.0065	0.0065	0.0065	0.007	0.007
r_{bl}^{min} ($m.s^{-1}$)	65	70	65	65	65	20	20	25	25	20	20
r_{bl}^{max} ($m.s^{-1}$)	95	100	95	100	95	55	55	45	45	50	50

728

729

730

731

732 **Appendix E: The Dynamic Roughness Parameterization Method**

733

734 In the Su et al. (2001) method, the roughness height for momentum transfer is calculated as:

$$z_{0m} = h_c \left(1 - \frac{d_0}{h_c}\right) \exp\left(-\frac{\kappa}{\eta}\right) \quad \text{E1}$$

735 where h_c is the canopy height and η is the ratio of friction velocity to the wind speed at the736 canopy top, calculated as $\eta = c_1 - c_2 \exp(-c_3 C_d LAI)$ with $c_1 = 0.32$, $c_2 = 0.264$, $c_3 = 15.1$ and737 the drag coefficient $C_d = 0.2$. The roughness length for heat transfer (z_{0h}) can be derived by738 assuming an exponential relationship between z_{0m} and z_{0h} as $z_{0h} = z_{0m} / \exp(\kappa B^{-1})$, where B^{-1} is739 the inverse Stanton number. To estimate the κB^{-1} parameter, the method of Su et al. (2001)

740 suggests:

$$\kappa B^{-1} = \frac{\kappa C_d}{4C_t \beta \left(1 - \exp\left(-\frac{n_{ec}}{2}\right)\right)} f_c^2 + 2f_c f_s \frac{\kappa \eta z_{0m} / h_c}{C_t^*} + \kappa B_s^{-1} f_s^2 \quad \text{E2}$$

741 where f_c is the fractional canopy coverage and f_s is its complement (for soil coverage). C_t is742 the heat transfer coefficient of the leaf, C_t^* is the heat transfer coefficient of the soil and n_{ec} is

743 within-canopy wind speed profile extinction coefficient.

744 As noted by Su (2002), the first term of equation E2 follows the full canopy model of Choudhury and

745 Monteith (1988), the third term is that of Brutsaert (1982) for a bare soil surface and the second

746 term describes the interaction between vegetation and a bare soil surface. Following Brutsaert

747 (1999), for a bare soil surface the κB_s^{-1} is calculated as $\kappa B_s^{-1} = 2.46 Re_*^{1/4} - \ln(7.4)$ with Re_* being

748 the Reynolds number. More details about the methodology and formulation are available in Su et al.

749 (2001) and Su (2002).

750

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965 **Impact of model structure and parameterization on Penman-Monteith type**
966 **evaporation models**

967 **6 List of Figures**

968

969 Figure 1: Location of the eddy-covariance towers used to provide forcing and validation data in this
970 study, derived from Ershadi et al. (2014)

971

972 Figure 2: Performance of the Penman-Monteith (PM) model in response to adjusting the resistance
973 parameterization. *RE* is relative error and *NSE* is the Nash-Sutcliff efficiency, with each point showing
974 the overall statistic for a particular tower. The x-axis displays the various biomes, with towers in each
975 biome arranged from left to right (e.g. G1 to G4 for grassland). The numbers at the bottom of the
976 *NSE* plot reflect the average *NSE* (i.e. NSE_{avg}) of the different scenarios for each biome type.

977

978 Figure 3: Performance of the Shuttleworth-Wallace (SW) model in response to adjusting the
979 resistance parameterization. *RE* is relative error and *NSE* is the Nash-Sutcliff efficiency, with each
980 point showing the overall statistic for a particular tower. The x-axis displays the various biomes, with
981 towers in each biome arranged from left to right (e.g. G1 to G4 for grassland). The numbers at the
982 bottom of the *NSE* plot reflect the average *NSE* (i.e. NSE_{avg}) of the different scenarios for each biome
983 type. The *RE* for S2 tower in the SW⁴ scenario and *NSE* for D4 tower in the SW⁰ scenario are out of
984 range, so their values are included on the plot.

985

986 Figure 4: Performance of the Mu model in response to adjusting the resistance parameterization. RE
987 is relative error and NSE is the Nash-Sutcliff efficiency, with each point showing the overall statistic
988 for a particular tower. The x-axis displays the various biomes, with towers in each biome arranged
989 from left to right (e.g. G1 to G4 for grassland). The numbers at the bottom of the NSE plot reflect the
990 average NSE (i.e. NSE_{avg}) of the different scenarios for each biome type.

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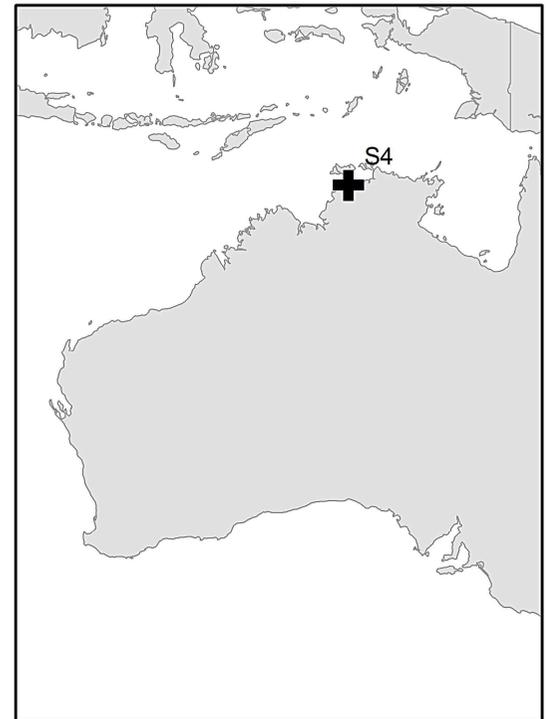
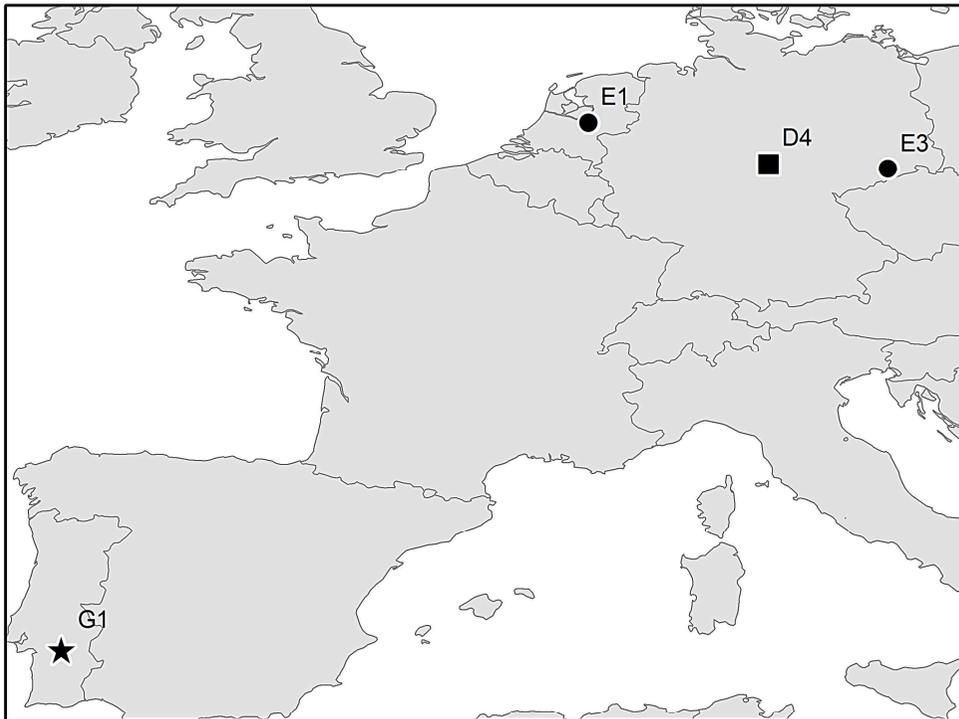
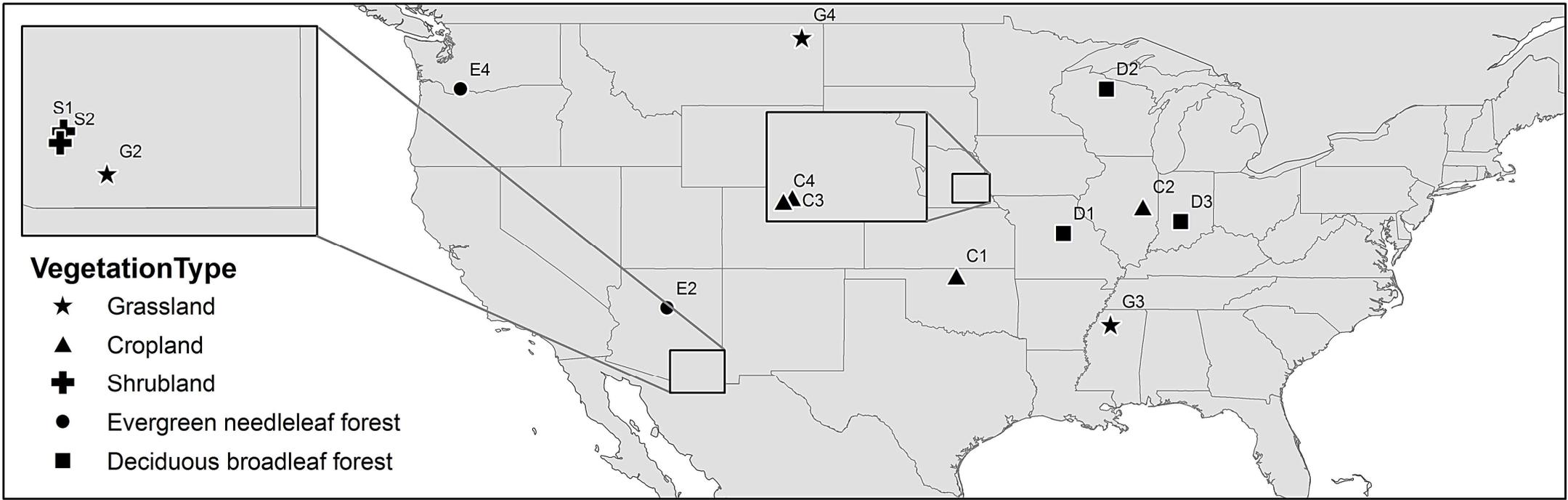
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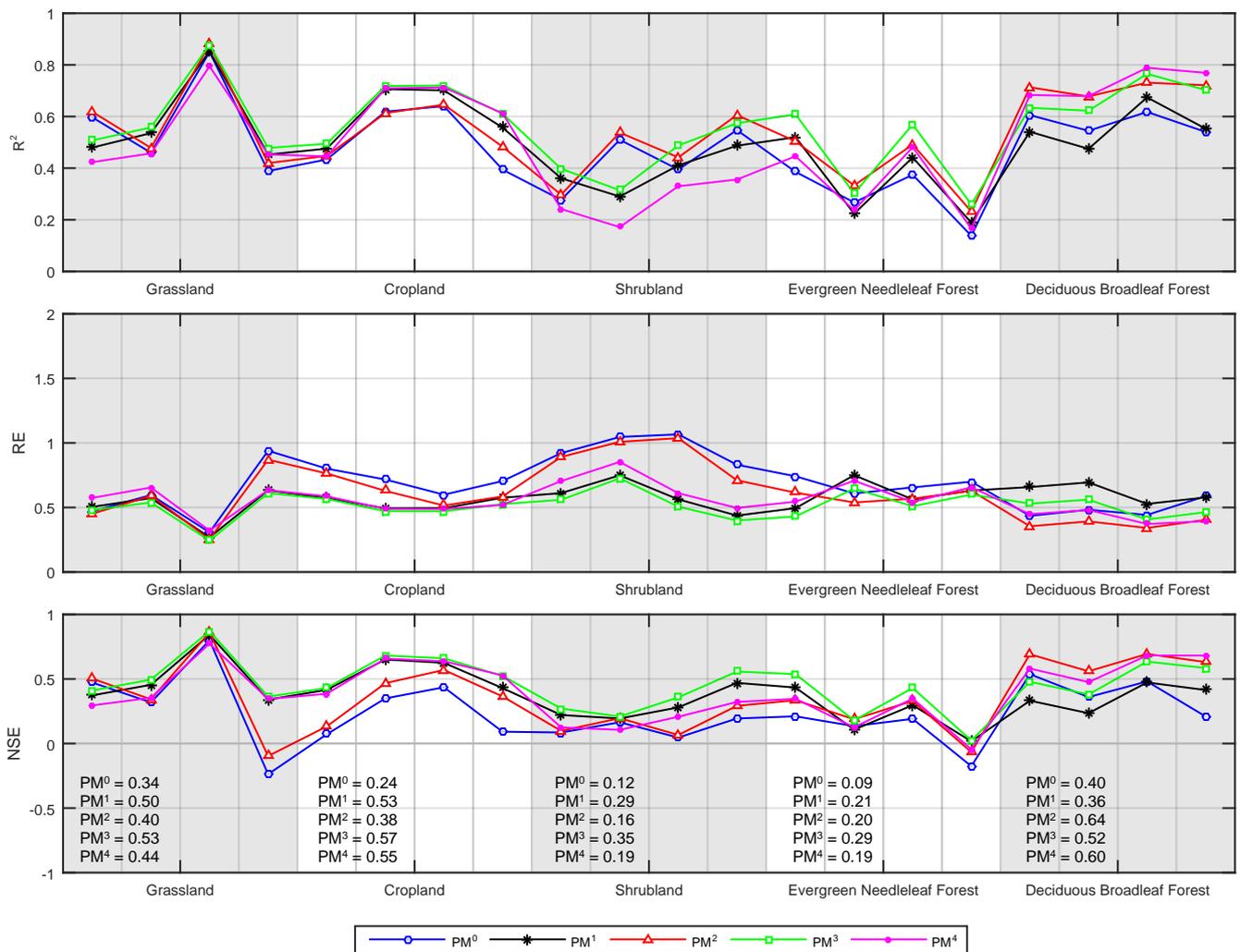
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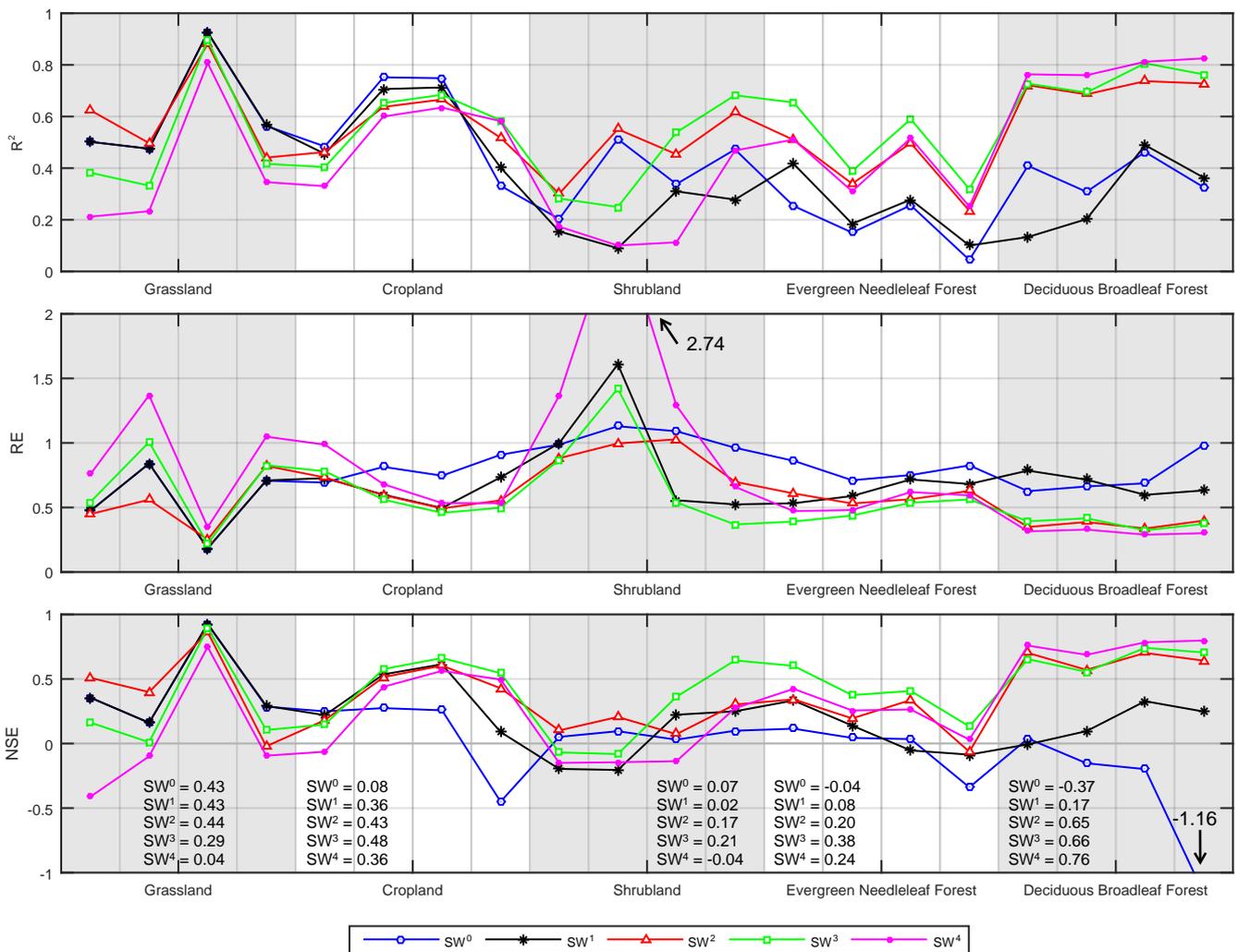
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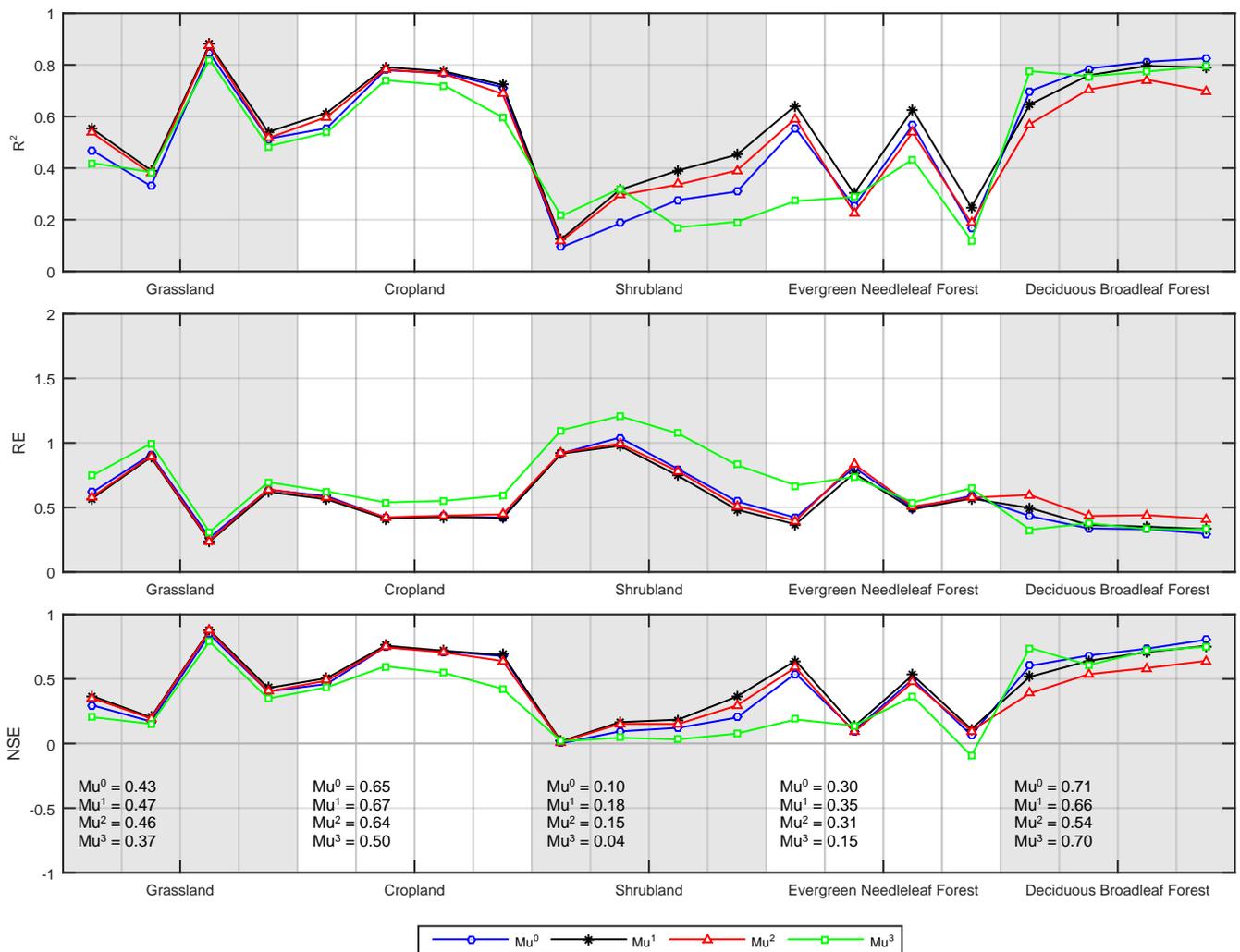
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RIPT





999 Highlights

- 1000 • Evaluated three Penman-Monteith type models with multi-year data from 20 flux towers
1001 over 5 biomes
- 1002 • Fourteen unique model configurations were developed to identify impact of resistance
1003 schemes
- 1004 • No particular model configuration consistently outperformed others
- 1005 • Considerable model variability was observed both within and between different biomes
- 1006 • Results provide guidance on model selection and performance across typical biome types
- 1007
- 1008